

College of Engineering, Pune

(An Autonomous Institute of Govt. of Maharashtra)

End-Semester Examination

EE402 - Control Systems-II

Year: - Final Year B. Tech

Academic Year: 2012-13

Time: 2.00 PM - 5.00 PM

Branch: Electrical

Date: 23-11-2012

Max. Marks: - 50

Instructions:

1. All Questions are Compulsory.
2. Figures to the **RIGHT** indicate **FULL** marks.
3. Make suitable assumptions, if necessary and state the same.
4. Use of non-programmable pocket calculator is allowed.

Q.1 For the unity feedback system given by _____ (08)

Design Phase-LEAD compensator to meet the following specification

1. Settling time $\leq 4\text{sec}$
2. Peak over shoot for step input $\leq 25\%$

Draw root locus of compensated and uncompensated system

Q.2 Design Phase-LEAD compensator via **FREQUENCY RESPONSE** for the system with open loop transfer function given by _____ (08)

$$G(s) = \frac{K}{S(S+2)}$$

The system is to be compensated to meet the following specifications:

1. Steady state error $\leq 5\%$ for ramp input.
2. Phase margin $>45^\circ$

Draw the bode diagram for uncompensated and compensated system.

Q.3 A nonlinear system shown in Fig. 3 with,

$$G(s) = \frac{K}{s(5s+1)(10s+1)}$$

- 1) Find the describing function of the nonlinearity.
- 2) Determine the system's stability.
- 3) Determine K and oscillation frequency ω when self-oscillation amplitude is $X = \frac{1}{\pi}$.

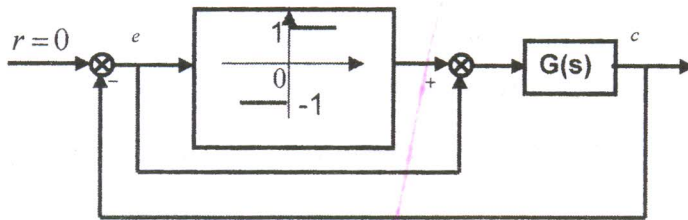


Fig.3

----- (10)

Q.4

- a) Using power series method to find inverse Z transform of the following function

----- (06)

$$G(z) = \frac{z^3 + 2z^2 + 1}{z^3 - 1.5z^2 + 0.5z}$$

- b) Derive State space representation of discrete time system represented by

$$G(z) = U(z)/E(z) = K(z+1)/(z^2-1) \quad \text{----- (06)}$$

Q.5

- a) Explain Zero Order Hold. Write the transfer function of ZOH and draw its frequency response.

----- (06)

- b) For a discrete -time system whose characteristic equation is given by

$$1 + KG(z) = 1 + \left(\frac{0.368z + 0.264}{z^2 - 1.368z + 0.368} \right) K$$

Applying Jury's test for stability of discrete time system, find K such that system is stable.

----- (06)